PATENT Docket No.: TW000002 Customer No. 000024737

## **Listing of Claims:**

1. (Currently amended) A method for merging a pair of overlapping twodimensional (2D) images, wherein the images comprise projections of a single threedimensional (3D) scene, said method comprising:

selecting at least four feature points in the 3D scene within an overlapping region of the pair of 2D images,

finding 2D coordinates of points in both images corresponding to the selected feature points, the 2D coordinates being found with respect to original coordinate systems in the two images,

translating <u>coordinates</u> of the 2D <u>coordinates</u> found <u>in</u> the original coordinate systems of the two images <u>by a chosen translation</u>, <u>wherein the translation is chosen</u> to substantially minimize <u>in a translated coordinate system</u>, <u>on</u> average, <u>numerical</u> coordinate ranges <u>of coordinate values</u> of the 2D coordinates found,

determining <u>first projective transformation</u> parameters of a substantially optimal projective transformation <u>in the translated coordinate system</u> relating corresponding translated coordinates <u>of the 2D coordinates found</u> in the two images,

determining second projective transformation parameters of the a projective transformation for application in the non-translated original coordinate systems of the two images, wherein determining the second projective transformation parameters comprises by altering the first projective transformation parameters in the translated coordinate systems system using translation vectors that ensure an equivalence of (i) the projective transformation in the original coordinate systems and (ii) the projective transformation in the translated coordinate systems is true, and

merging the two images into a <u>single</u> composite <u>2D</u> image by (i) transforming one <u>2D</u> image according to the projective transformation <u>for application in the non-translated</u> <u>original coordinate systems of the two images</u> into a transformed <u>2D</u> image <u>using the second projective transformation parameters</u> and (ii) combining the transformed <u>2D</u> image with the other <u>2D</u> image.

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- 2. (Previously presented) The method of claim 1, wherein selecting comprises automatically selecting feature points with sufficient surrounding structure for accurately matching of the corresponding 2D coordinates in the two images.
- 3. (Previously presented) The method of claim 1, wherein translating comprises determining a translation for each image as an average of the 2D coordinates in the respective image.
- 4. (Currently amended) The method of claim 1, wherein determining the <u>first</u> projective transformation parameters of the substantially optimal projective transformation in the translated coordinate system comprises performing a singular value decomposition.
- 5. (Currently amended) The method of claim 1, wherein determining the <u>first</u> projective transformation parameters of the substantially optimal projective transformation in the translated coordinate system comprises performing a minimization of an error function.
- 6-12. (Cancelled).
- 13. (Currently amended) A computer readable medium program product comprising encoded program computer readable media having a set of instructions for causing a processor to perform executable by a computer, the instructions being configured for merging a pair of overlapping two dimensional (2D) images that comprise projections of a single three-dimensional (3D) scene according to the method of claim 1.